





Thank you for purchasing this product! Please read the following statement carefully before use and, once used, it is considered to be an acceptance of all the contents. Please strictly observe and adhere to the manual installation with this product. Unauthorized modification may result in personal injury and product damage. We reserve the rights to update the design and performance of the product without notice.

This ESC is an industrial-grade component for unmanned aircraft. If you have more specialized application requirements, please contact us.

HW-SMAR5QDI II OO

Precaution

- Before connecting ESC to the related components, please ensure that all contact terminals are well insulated to prevent short circuit from damaging the ESC
- Ensure proper connection for the aircraft to operate normally and prevent unpredictable damage to the equipment
- Before using this ESC, please review the manual to ensure that the power system is correctly matched to avoid damage to the ESC due to wrong connectivity.
- Use only hi-power soldering station that is reliable for soldering work on the ESC.
- Do not use it when the external ambient temperature exceeds 65°C. The high temperature will destroy the ESC and may cause damage to the motor, and cause the machine to explode
- If you need to change the direction of rotation of the motor, you can change the sequence of any two-phase wires.
- The ESC is equipped with CAN function. When using the CAN function, the ESC ID and the throttle channel of the same aircraft cannot be the same, otherwise, the multiple ESCs will be recognized as
- The ESC does not come with CAN terminal resistor by default and needs to be matched uniformly across the whole machine.

02 Feature of product

- This ESC has a fixed propeller function. In order to use this function, it needs to be paired with a Hobbywing motor with a magnetic encoding board.
- Multi-rotor dedicated core program, the throttle response speed is greatly improved
- A built-in memory chip that records the ESC running data in real time and provides the black box function
- This ESC is equipped with nano-coating technology with a protection level of IP55, and IP67 can be customized.
- The microprocessor is powered by an independent voltage regulator IC, which has better anti-interference ability and greatly reduces the possibility of control loss.
- Uses shielded wires to improve anti-interference, shield external and self-interference, and improves signal quality. • BLDC square wave drive technology, good compatibility, a program can be compatible with a variety of motors.
- Using CAN communication, the input and output throttle, motor speed, bus current, bus voltage, capacitor temperature, MOS temperature, ESC status and other data can be monitored in real time. The communication protocol can be obtained by contacting Hobbywing.
- The factory default settings can meet the requirements of most applications with automatically adjustable timing, and is highly intelligent.
- Compatible with various flight controllers and throttle signals with a refresh rate of 50~500Hz
- . Using DEO (Driving Efficiency Optimization) drive technology, it has better throttle linearity and higher drive efficiency.
- You can use DataLink (optional) to upgrade the ESC program. For details, refer to the Datalink instruction manual or contact the manufacturer.
- Support flight controller upgrade ESC firmware. (Requires the use of flight controller)
- Throttle pulse width 1100-1940µs, solidified pulse width, not calibrated

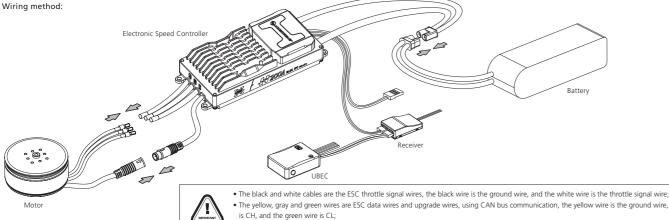
03 Product Specifications

ı		Continuous current Cooling wind speed 7m/s	Specification	BEC	Number of lithium battery cells(3.7V)		Weight (no wire)	Physical dimension (mm)	
	XRotor Pro-H200A-24S-BLDC-IPC-RTF-HW	100A	200A	None	245	DEO (on/off)	420g	138*68*32.5	ĺ

04 User Guide

Warning! The throttle of this ESC is fixed, and the throttle stroke cannot be calibrated.

Warning! This ESC has PWM throttle mode, CAN digital throttle mode, set which throttle mode to use, and the default response corresponds to the throttle mode Warning! Upon debugging the fixed propeller function, the motor will rotate for 4-6 seconds during calibration. Please remove the propellers for debugging to avoid accidental injury.



• The CAN wire is also a digital throttle wire and can be used in parallel

05 Normal start-up process

Turn on the remote control, push the hrottle stick to the lowest point

Connect the system to the battery, and the motor will beep " 123", indicating that the power system is ready, the self-test is over and you can take off at any time

06 Protection function description

This ESC is specially designed for industrial drones without low-voltage protection and over-heat protection.

When the motor fails to start normally within two seconds after pushing the accelerator, the ESC will shut down and the throttle stick must be placed at the lowest point again before it can be restarted. (The reason for this may be poor connection between the ESC and the motor or disconnected individual output wires, motor stalled, propeller blocked, etc.).

When the ESC detects that the motor is locked, the ESC will completely turn off the output and repeatedly try to restart the motor. Please land the aircraft as soon as possible if the motor is unable to be restarted. The power output can only be resumed after the power is turned off and restarted, and the fault is eliminated.

The ESC will shut down the output and keep trying to restart the motor when the instantaneous current is abnormal and exceeds 800A. If the motor fails to restart multiple times, it will return to

4) Over-heat warning This ESC has no over-heat protection. The warning will be sent through the data interface when the temperature of MOS is higher than 110 °C or the temperature of capacitor is higher than 100 °C. When there is a warning reported, if the temperature continues to rise, electronic components may be damaged. Please land the aircraft immediately or reduce the throttle output

5) Low voltage protection:

This ESC has no low-voltage protection. Some electronic components of the ESC will work abnormally when the voltage falls below 36V. Please land the aircraft immediately.

When the ESC detects that the throttle signal is lost, the output will be turned off immediately to avoid greater losses caused by the continued high-speed rotation of the propeller. After the signal is restored, the ESC will resume normal operation immediately

07 ID Setup

If there is no requirement, the default factory ID of the ESC is 1, the throttle channel is 1, and the bus speed is 500KHz

This function requires the additional purchase of DataLink data box

Before using this function, ensure that the computer system has installed Micosoft Visual C++ 2013 software in advance, otherwise it cannot operate normally

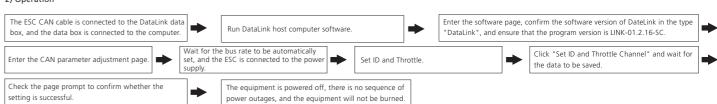
1) Connection

ESC---->DataLink data box "yellow gray green"---->"—CH1 CL1".

When changing the ID, please remove the paddle to avoid danger.

Connect the data box to the computer via USB.

For the same aircraft, different ESC IDs and throttles cannot be the same to avoid same ID recognizing as one ESC when using CAN function.



08 Fault data read

The ESC has its own fault storage function to store the times upon powering-on, flight time, and fault times information. It is convenient for flight fault analysis. This function needs to use DataLink data box, serial port assistant, and DataLink host computer software

Note: DataLink software can be obtained from Hobbywing official website, dealers, Hobbywing sales, and Hobbywing after-sales.

DataLink data box firmware version requirements: LINK-01.2.16-SC or later; serial port assistant requirements: USB to TTL protocol; DataLink host computer software requirements: fault storage version. It can be obtained on the official website. WeChat official account or after-sales service.

The DataLink box has three power supply methods (+5V), USB data cable, serial port assistant, and external power supply cable. You can choose one of the power supply methods, and you don't need to repeat the power supply.

Note: For detailed steps, please refer to the DataLink user manual.

Serial port assistant ----> DataLink data box "GND 5V TX RX" ----> "— + RX2 TX2" (please click here for the corresponding line sequence);

ESC---->DataLink data box "yellow gray green"---->"— CH1 CL1", multiple ESCs can be used in parallel.

2) Software operation



09 Firmware upgrade

Firmware upgrade is divided into two ways: computer online upgrade and flight controller remote upgrade. It supports online upgrade of multiple ESCs at the same time, and the upgrade port is CAN-ESC (Fast).

The flight control upgrade requires the use of flight control, and is not explained here.

Connect the computer and the DataLink data box with the USB data cable.

This function needs to use DataLink data box, special DataLink software for upgrade package, and USB data cable.

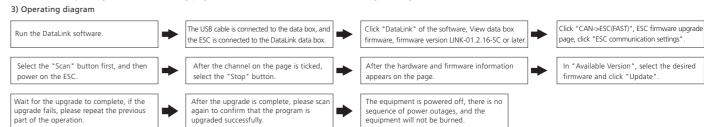
DataLink data box version requirements, LINK-01.2.16-SC or later; DataLink software can be obtained from Hobbywing official website, distributors, Hobbywing sales, and Hobbywing after-sales. Note: Before using this function, please ensure that the computer has installed Micosoft Visual C++ 2013 software, otherwise it cannot be used. An upgrade package usually only contains one program

for one ESC. For other ESCs, please obtain a new upgrade package. For details, please refer to the DataLink user manual.

ESC---->DataLink data box "yellow gray green"---->"---CH1 CL1". 2) Firmware acquisition

It can be obtained at the place of purchase, Hobbywing official website, dealers, Hobbywing sales and Hobbywing after-sales offices.

Note: It can only be upgraded from the existing program, and software and hardware cannot be upgraded together.



U Common failures and workaround

SYMPTOM	TONE	POSSIBLE CAUSES	POSSIBLE SOLUTIONS
Motor fails to start after power on	"Beep beep beep" rapid monophonic	Throttle not reset to zero	Push the throttle to the lowest point or recalibrate the throttle point
Motor fails to start after power on	"Beep, beep, beep,"(1 second for each interval)	Receiver throttle channel has no throttle signal output	Check whether the transmitter and receiver operates normally Check whether the throttle control channel wiring is normal
The power-on voltage is lower than 36V	"Beep, beep" (interval 1 second)	Battery voltage is too low	Replace with a suitable fully charged battery
The power-on voltage is higher than 108V	"Beep, beep" (interval 1 second)	Battery voltage too high	Replace with a suitable fully charged battery
The motor stops or restarts		The motor is not compatible with the ESC	Replace the motor, or replace the propeller
There is no sound during the self-test of the tmotor, but the motor can rotate	There is no prompt sound during self-test, and the motor rotates	Driver exception	Replace ESC; Return to factory for repair.
The motor cannot start normally, accompanied by "click" click" jitter	There is no prompt sound during the self-test, and the motor is unable to rotate	Motor phase loss	Check phase connection; Check motor; If there is no problem with the motor and connection, return the ESC to the factory for repair.

$1\overline{1}$ Instructions for the use of fixed propeller function

This function requires the use of DataLink data box, dedicated DataLink host computer software, dedicated parameter configuration file, and USB-TTL module.

Note: Please confirm that the USB-TTL module driver has been installed correctly; the DataLink data box version requirement is LINK-01.2.16-SC or higher; before using this function, please ensure that the computer has installed Micosoft Visual C++ 2013 software. If it is not installed, it will not work. Please refer to the DataLink user manual for details. 1) Connectivity

USB-TTL module connects the computer and DataLink data box

① Connect the ESC three-phase wire to the motor (no sequence), and the 6pin connector is correctly connected to the motor magnetic encoding board;

② ESC CAN signal line ----> DataLink data box "yellow gray green" ----> "— CH1 CL1" ; ③ USB-TTL module --->DataLink data box, TTL-USB TX is connected to Datalink RX, TTL-USB RX is connected to Datalink TX.

2) Software acquisition The PC software and configuration files can be obtained at the place of purchase, Hobbywing official website, Hobbywing sales, and Hobbywing after-sales service.

3) Operation Slide the slider to "Serial Port" in the upper right

Run DataLink software.





Manually move the motor to the desired angle, select About 5 seconds after the previous step ends, it will automatically enter the target angle positioning. It can also be closed through "Calibrate" and click "Write to ESC". At this time, the 'Close Positioning', and the fixed propeller angle can be adjusted ESC is in the calibration zero position. Please do not apply osition and whether the four-digit XXXX status code appears. external force to the motor. based on the target angle through 'Rotate XX Angle'.